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TITLE: Portable Body Temperature Conditioner

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13. SUPPLEMENTARY NOTES

14. ABSTRACT Many patients become hypothermic after severe injury due to environmental exposure during transport. These patients also have decreased thermoregulation due to blood loss. Normal core body temperature is defined as 37^oC and core body temperature below 35^oC and above 40^oC is defined as hypothermia and hyperthermia respectively. Studies have shown much better outcomes for patients with either trauma or hypothermia compared to patients with both trauma and hypothermia. Additionally, studies have shown that decreasing the hyperthermic patient's core body temperature rapidly to 38^oC lowers the incidence of complications and the risk of death. Currently, the most effective treatments for dysthermic patients involve active convective heating/cooling devices. However, current devices require heavy or bulky equipment not suitable for military applications. This study focuses on developing a portable in-field, battery operated body temperature conditioning system. The heating/cooling system has been designed to maximize efficiency allowing for a reduction in component and battery weight. Additionally, rechargeable lithium-ion batteries are being utilized to allow for military use during medical evacuations in the absence of a reliable power source. To evaluate the heating/cooling capacity of the device, patient simulation testing will be performed through the use of a thermal manikin. This research will identify specific design improvements to be implemented in a reiterative process, ultimately leading to an efficient portable body temperature conditioning device suitable for military applications.

15. SUBJECT TERMS
Hypothermia, Circulating Water-blanket, Trauma, Hyperthermia, Military

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Portable Body Temperature Conditioner

Principal Investigator: Timothy D. Browder, MD
Co-Investigator: Deborah Kuhls, MD
Co-Investigator: John Fildes, MD

Table of Contents

INTRODUCTION:

Many patients become hypothermic after severe injury due to environmental exposure during transport and decreased ability of thermoregulation due to blood loss. Normal core body temperature is defined at 37°C and hypothermia occurs at a core body temperature below 35°C. Studies have shown much better outcomes for patients with either trauma or hypothermia compared to patients with both trauma and hypothermia [1-6]. Additionally, hyperthermia occurs at core body temperatures above 40°C. Hyperthermia can progress quickly and occurs as the result of excessive heat exposure or strenuous physical activity in hot environmental conditions. Studies have shown that lowering the patient's core body temperature rapidly to 38°C improves complications and lowers the risk of death [7-8]. Currently, the most effective treatments for hypo-hyperthermia patients involve active convective heating/cooling devices [1,3-8]. However, these methods require heavy or bulky equipment and are not practical for military applications in the field. The evidence for active heating/cooling treatments for trauma patients prompted this study to develop a portable battery operated in-field body temperature conditioning device for military use under extreme thermal conditions. This portable device will promote normothermic conditions in injured or ill patients during medical evacuation. The body warmer consists of two elements: the heating/cooling module and a full body water circulating blanket. The circulating water blanket is composed of multiple layers including a heat exchanger with circulating passageways, insulation, and a contact surface allowing direct surface contact with the patient's body. The heating/cooling module comprises an ultra-high efficiency vapor compression cooler/heat pump with advanced viable speed drive. The heating/cooling system also utilizes advanced refrigerant flow control for variable speed operation yielding maximum energy efficiency. By designing the heating/cooling system for maximum energy efficiency, smaller batteries are able to be used for equivalent operating periods while reducing the overall weight of the device. Additionally, the variable speed vapor compression system can be powered from either DC/AC power systems or operated via battery power. Rechargeable lithium-ion batteries will be used to minimize additional accessories. Overall, the heating/cooling module of the body warmer is designed to allow for controlled heating or cooling of a patient in an extremely efficient manner while minimizing battery weight. Additionally, upon completion of the prototype for the portable body temperature conditioner, patient simulation testing will be performed to measure the heating/cooling capacity of the device. A thermal manikin has been purchased to simulate various conditions as part of the patient simulation testing. Quality system regulation (QSR) is required for 510(k) submission and FDA clearance of medical device. University of Nevada School of Medicine (UNSOM) department of Surgery Research Laboratory and Rocky Research has begun to implement QSR Standard Operating Procedures (SOP's) which will be ongoing throughout the duration of the project.

BODY:

Problems

There was one significant administrative setback in the first quarter of year one. This was in regards to a 5 – 7 week delay due to establishing an account for the DOD award number W81XWH-11-1-0792 by Board of Regents, Nevada System of Higher Education (NSHE) on behalf of University of Nevada, Reno (UNR) and signing a sub-award by Rocky Research to begin work on a Portable body temperature conditioner. This setback caused the project to be about two months behind. However, a no cost extension of one year was submitted and approved by the United States Army Medical Research Acquisition Activity (USAMRAA) in the third quarter of year one, extending the project completion date to October 2013. This resulted in a readjustment of the timeline for the major milestones, allowing for the project to get back on schedule.

Another recent setback involving the purchase of the thermal manikin for patient simulation testing has resulted in another small delay regarding the completion of task 2 (Prototype Fabrication). The thermal manikin "Newton" purchased from Measurement Technology Northwest (MTNW) and was initially scheduled to be delivered by the end of August 2012. However, a delay in manufacturing by MTNW pushed the delivery date to mid-September 2012. Rocky Research requires the thermal manikin to perform final prototype breadboard testing under patient simulated loading conditions. The delay in manufacturing has resulted in a delay in finishing task 2 (Prototype fabrication) on schedule. Currently, the thermal manikin has been received and task 2 is expected to be completed within the first quarter of year two.

Gantt Chart (Outlining current progress and current schedule of proposed project)

[Gantt chart. Green when task is completed. Light green for task that is on schedule and active. Yellow when it is delayed; a red line showing when it is to start and when anticipate it to be completed. Blue for task that is yet to start.]

Task	Y1Q1	Y1Q2	Y1Q3	Y1Q4	Y2Q1	Y2Q2	Y2Q3	Y2Q4	Status
1 Design of the System	▓	▓							**Completed**
2a Bread board Fabrication			▓						**Completed**
2b Breadboard Testing			▓	▓					**Completed**
2c Prototype Fabrication				▓					**Delayed (require additional testing with manikin)**
3a Functional Testing					▓				**Yet to Start**
3b Performance Testing (Manual Control)					▓	▓			**Yet to Start**
3c Control Logic Testing						▓	▓		**Yet to Start**
3d Modifications as necessary and retest							▓	▓	**Yet to Start**
4a Write test and validation methods				▓	▓				**On Schedule**
4b Receive and training on thermal manikin/software				▓	▓				**On Schedule**
4c Validation of thermal manikin					▓	▓			**Yet to Start**
4d Patient Simulation Testing						▓	▓	▓	**Yet to Start**

Task 1: Design of the System (Months 1 – 6). **Completed**

<u>Analytical Modeling</u>

As part of Task 1 Design of the System, a commercial software called Modelica/Dymola is being used to develop the prototype analytical model and its cycle components. The model will be used to select components and evaluate performance, size and weight of the system.

Modelica is an object-oriented language for modeling of large, complex, and heterogeneous physical systems. It is used for multi-domain modeling in robotics, automotive and aerospace applications involving mechanical, electrical, hydraulic and control subsystems, process oriented applications and generation and distribution of electric power. Models in Modelica are mathematically described by differential, algebraic and discrete equations. No particular variable needs to be solved manually. A Modelica tool will have enough information to decide that automatically.

Overview description of main component models in the simulation are shown below, The cycle is shown in Figure 1:

Compressor:
- Reciprocating and Scroll compressors
- Quasi-steady state approach for calculation of enthalpy change and mass flow
- Volumetric and isentropic efficiency are provided either as parameters or by characteristic map or by polynomials
- Mechanical connector for interaction with motor/engine model

Pulsing Thermal Expansion Valve:

- Expansion is treated as isenthalpic
- Quasi-steady state approach for calculation of mass flow according to IEC 60534-2-1 standard
- The flow coefficient is given via an input-connector
- Physical behaviour of bulb is modeled using maximum operating temperature MOT and
- maximum operating pressure MOP

Heat exchangers:

- Cross-counter-flow heat exchangers for evaporator and condenser geometries, and also for heater core with coolant
- Different number of passes and layers are possible
- Parametrization features enable more generalized and simplified implementation of new heat exchangers
- Internal refrigerant/refrigerant heat exchanger
- Coolant/refrigerant heat exchanger

Accumulator:

- High pressure accumulator built up from phase separator, flow resistance and pipe. Low pressure receiver also built up from fundamental, physically modelledcomponents

Wall models:

- Capacitive and linear models of walls
- Pipes and Volumes
- Discretized and lumped pipe models with and without heat loss
- Lumped volumes, e.g. for modeling of oil filter in combination with flow resistance

Flow resistance:

- Lumped models calculating the pressure drop using a constant or mass flow dependent friction factor.
- Correlation for louvered fins based on a Colburn factor computed for air flow through corrugated louvered fins. The following empirical correlation by Chang and Wang (1997) is used for the Colburn factor j [9].

Pressure drop of refrigerant:

- Reynolds-dependent correlations for 1-phase flow (laminar, turbulent, transition region)
- For 2-Phase flow a correlation with the 2-phase multiplier is implemented

Heat transfer correlations on the refrigerant and air side:

- All choices for the heat transfer correlation on the refrigerant side are based on the common variables e.g. htpars geometry record,mdot mass flow, Re, Fr and Pr characteristic numbers. The correlations are mostly based on the VDI-Warmeatlas (VDI Heat Atlas).
- For the air–side specialized Colburn correlations for louvers are used.
- All two-phase correlations also take into account the length of the twophase region in volumes which have a phase boundary. The twoPhaseFraction variable is used to weigh together two-phase and one-phase correlations into an overall heat transfer coefficient.
- The heat transfer coefficient for one-phase pipe flow is modeled continuously with Reynolds-dependent Nusselt correlations covering the entire Reynolds number region. The correlations are spliced together over the transition region between laminar and turbulent flow. The following assumptions and boundary conditions apply:
    - Newtonian fluid
    - 1-phase pipe flow
    - laminar and turbulent flow
    - constant wall temperature
    - thermally and hydraulically developed flow

The model being developed is shown below. Modeling results will be reported in detail in the next status reports.

7
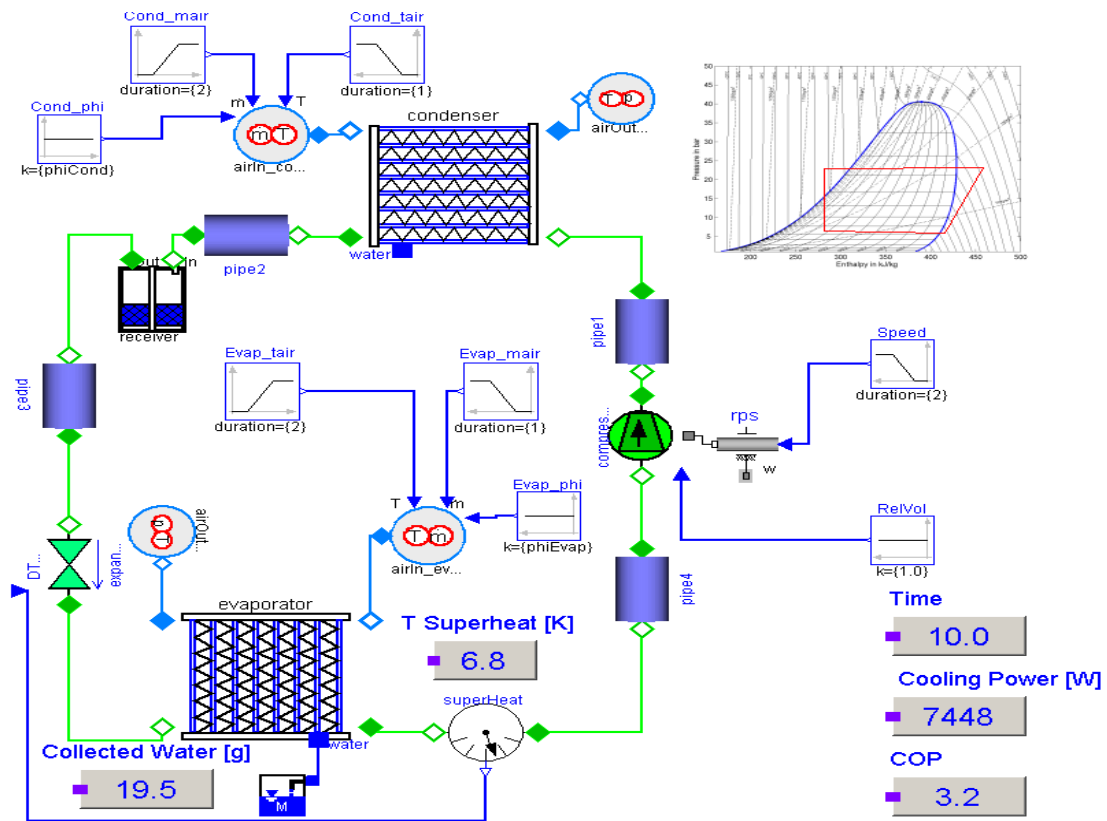
Figure 1. Simulation Model with Modelica components

Refrigerant Selection

Another step in developing the system is the selection of the most adequate refrigerant for a given operating condition, observing the theoretical efficiency, necessary refrigerant flow and finally the volumetric displacement required for the compressor. The ambient temperature of 35°C (95°F) and considered refrigeration cycle was that shown in figure 2.

Figure 2. Thermodynamic cycle (Pressure-Enthalpy diagram)

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In the considered thermodynamic cycle, evaporator enthalpy difference refers only to the useful heat exchanged, with isenthalpic expansion in process 3-4 and saturated vapor in 1', without overheating in the evaporator and without sub cooling in the condenser. At the beginning of compression, vapor super-heating is considered at an ambient temperature of (25°C). Process 1-2 refers to an isentropic compression. These conditions represent the lowest theoretical isentropic performance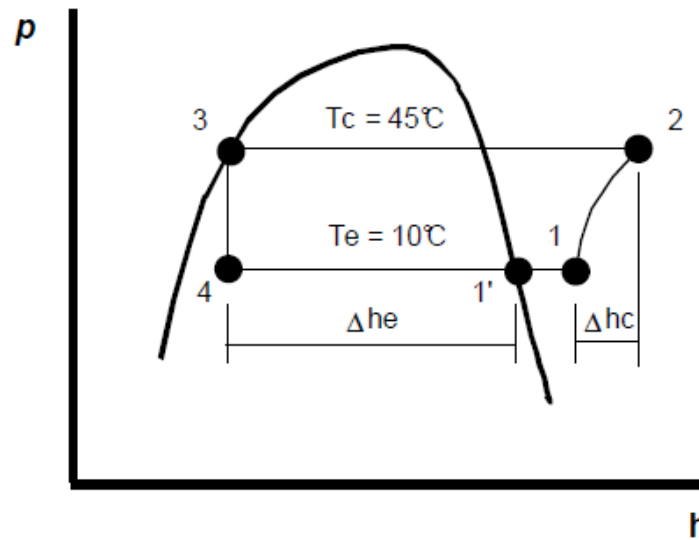 and the condition that is the closest to the real application. The cycle performance will be calculated using the simulation model being developed.

Design for Efficiency and Compactness

A major obstacle to building compact vapor compression systems has been the absence of commercially available and affordable miniature compressors in the fractional-kilowatt range that would fit within a small space. Recently, such a compressor has been developed and become available that is only 5.6 cm in diameter, 7.6 cm high, and weighs about 600 g. A photograph of the mini-compressor is shown in Figure 3. Figure 4 shows a preliminary layout of the major system components.
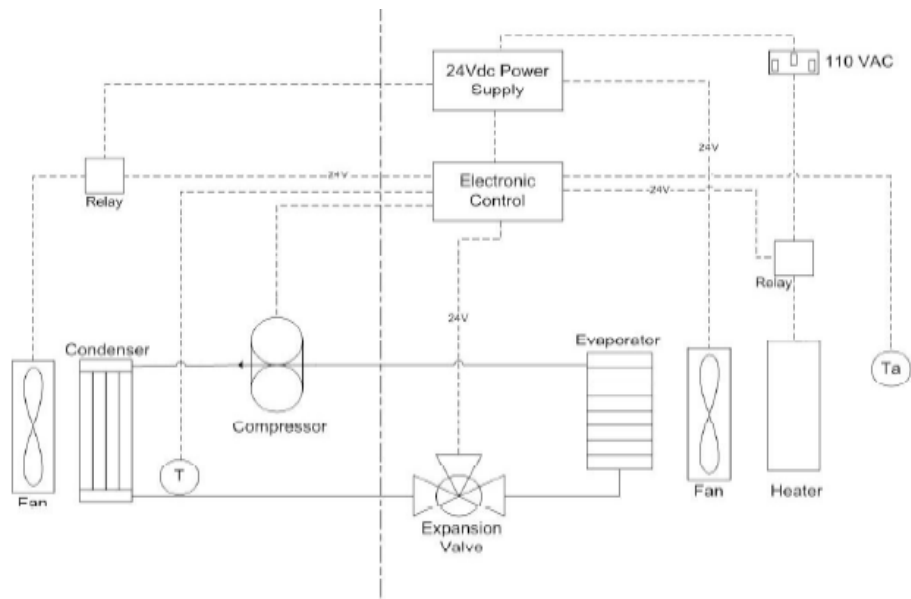

Figure 3. Miniature Compressor

Figure 4. Preliminary Layout of System Components

Due to space limitations and compact requirements, the design employs other high performance components including custom designed evaporator and condenser heat exchangers. In order to keep the heat transfer surfaces clean from airborne particulates, an air filter can be included in the sealed air system. The reduction in size has a strong correlation with compressor operating frequency for various aspects. The first is fundamental, and refers to the volumetric displacement occurring over a period of time. The greater the frequency the smaller the displaced volume in each compression cycle and, thus, the smaller the compression mechanism dimensions can be. On the other hand, the space available for installing the valves becomes smaller. Thus, the definition of compression pump becomes a simultaneous optimization of the mechanism variables related to the displaced volume and valve system, as an operating frequency function. It is important to note that the volumetric yield is not linear due to operating frequency, as there are other variables such as dead volume and leakage between piston and cylinder which affect it. This calculation considers the re-dimensioning of the valves in order for them to operate adequately at high frequency. The behavior of the volumetric efficiency as a function of the operating frequency is shown in figure 5.
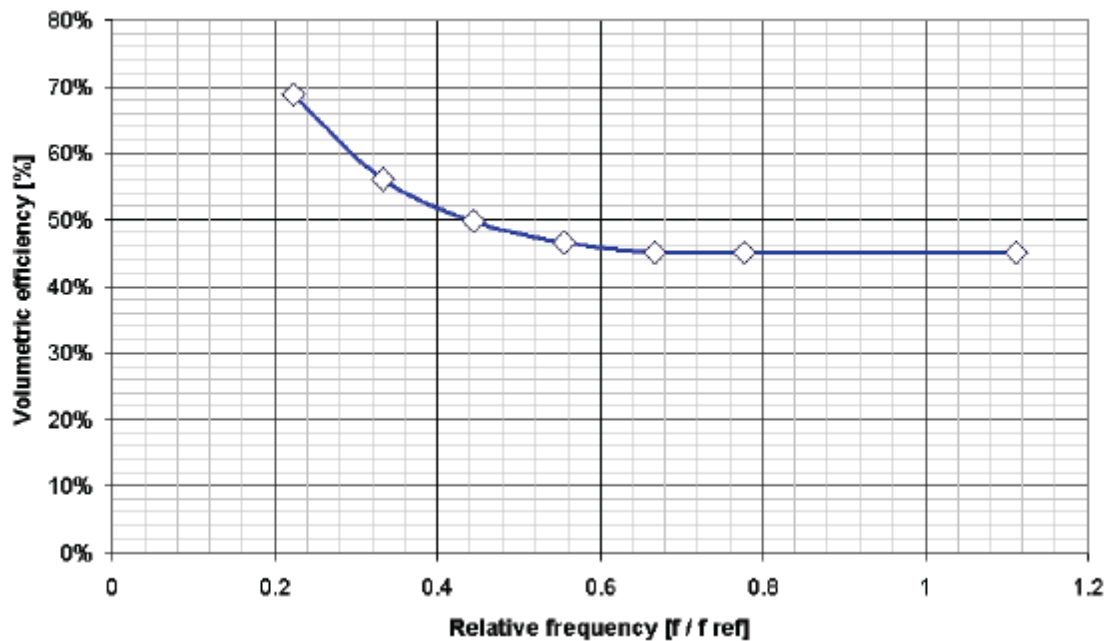
Figure 5. Volumetric efficiency according to running frequency

As part of the design and selection of the vapor compression system different miniature compressors from three different vendors have been studied and analyzed. Three compressors studied are: 1) a rotary compressor manufactured by Engel, and 2) a reciprocating compressor manufactured by Hitachi and 3) Rotary compressor made by Aspen.

The Aspen miniature rotary compressor operates with a rolling piston mechanism. It uses a brushless electric motor that runs on 24 V DC power supply. Figure 6 shows the important external dimensions of the compressor, while its specifications are given in Table 1.

Table 1. Compressor Specifications

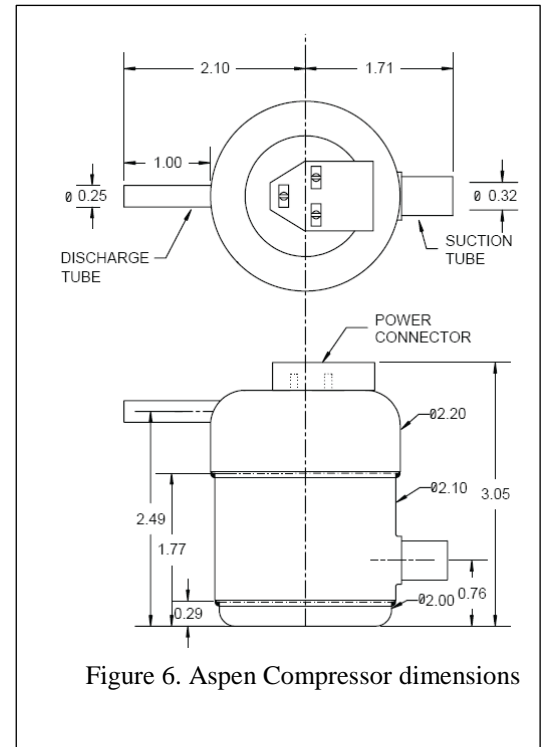| Refrigerant	R134a
Lubrication oil	Nu Calgon RL68H Polyol ester oil
Compressor type	Rotary (rolling piston)
Compressor displacement	1.4 cc
Compressor speed	Variable
Speed range	2000 – 6500 RPM
Motor	Brushless DC
Voltage	24 V DC
Maximum current	12 Amps continuous
Evaporator temperature range	-18 – 24 °C
Condenser temperature range	27 – 71 °C
Maximum discharge temperature	130 °C
Maximum compression ratio	8:1
Refrigerant	R134a
Lubrication oil	Nu Calgon RL68H Polyol ester oil
Compressor type	Rotary (rolling piston)
Compressor displacement	1.4 cc
Compressor speed	Variable
Speed range	2000 – 6500 RPM
Motor	Brushless DC
Voltage	24 V DC
Maximum current	12 Amps continuous
Evaporator temperature range	-18 – 24 °C
Condenser temperature range	27 – 71 °C
Maximum discharge temperature	130 °C
Maximum compression ratio	8:1

Figure 6. Aspen Compressor dimensions

Measurements and Data Reduction

Experimental tests on the compressor are conducted at three different suction pressures, four pressure ratios, and three compressor rotational speeds. The following parameters are directly measured using the instrumentation:

1) Suction pressure and temperature
2) Discharge pressure and temperature
3) Refrigerant mass flow rate
4) Electrical power consumed by the compressor (by measuring DC voltage and current supplied to the main circuit board)
5) Compressor rotational speed (by measuring the DC voltage supplied to the secondary circuit board).

Results

Table 2 provides a comparison of these compressors. It clearly demonstrates that the sizing of the compressor holds the key to an efficient miniature refrigeration system for electronics cooling. The two compressors tested by Trutassanawin et al. (2006) offered relatively poor performance [10]. The Aspen rotary compressor, however, has a much smaller displacement volume and provides good system performance.

Table 2. Compressor Results Comparison

	Engel rotary compressor	Hitachi reciprocating compressor	Aspen rotary compressor
Dimensions			
Height (mm)	166	195	78
Length/diameter (mm)	85	204	56
Width (mm)	-	13 mm	-
Displacement (cc)	2.3	2.0	1.4
Weight (kg)	2.8	4.3	0.6
Performance with refrigerant R134a			
Pressure ratio	2.1 – 3.2	1.9 – 3.0	2.0 – 3.5
Speed (rpm)	2000	2000	3000 – 6000
Volumetric efficiency (%)	57.0 – 79.3	58.1 – 73.0	73.2 – 90.5
Overall isentropic efficiency (%)	40.6 – 59.5	43.2 – 56.5	44.1 – 70.3
Cooling capacity (W)	130.1 – 256.4	152.2 – 208.8	160.2 – 489.6
System COP	3.0 – 5.7	2.6 – 3.7	2.1 – 7.4

Implementing QSR

The University of Nevada School of Medicine (UNSOM) hired a Food and Drug Administration (FDA) consultant to begin work on implementing a Quality System Regulation (QSR) at Rocky Research and UNSOM, department of Surgery Research Laboratory. The QSR will be ongoing throughout the duration of the project and is required for 510(k) submission and FDA clearance of the medical device. The following QSR Standard Operating Procedures (SOP's) have been implemented at UNSOM department of Surgery Research Laboratory.

1. "Creation, Format, and Review of SOP's" – Defines the procedure for the creation, format, and review of SOP's within UNSOM department of Surgery Research Laboratory

2. "Quality Policy" – Defines overall intentions and direction with respect to quality within UNSOM department of Surgery Research Laboratory.

3. "Management Responsibility and Organization Policy" – Defines UNSOM department of Surgery Research Laboratory management responsibility, objectives and commitment to quality.

4. "Validation Policy" – Outlines policy for qualification, validation, and calibration of equipment, processes and systems throughout UNSOM department of Surgery Research Laboratory.

5. "Training" – Procedure of training and training documentation for all UNSOM department of Surgery Research Laboratory personnel subject to Good Manufacturing Practices (GMP).

6. "Laboratory Entry and Review Guide" – Procedure to provide uniformity in the practice of recording data and to assure compliance with GMP data recording requirements.

7. "Significant Figures and Rounding" – Establishes convention for rounding of analytical data obtained in the laboratory or provided to UNSOM department of Surgery Research Laboratory.

8. "Instrument and Equipment Calibration and Maintenance" – Policy and system for instrument calibration and maintenance. Policy applies to all instruments used in manufacturing, processing, testing, packaging, labeling, and holding of devices with UNSOM department of Surgery Research Laboratory.

9. "Regulatory Inspection Policy" – Define Good Manufacturing Practice (GMP) Inspections Policy for Regulatory Agencies visiting UNSOM department of Surgery Research Laboratory.

10. "Issuance and Control of Notebooks/Logbooks" – Procedure for issuance and control of hardbound notebooks including logbooks and laboratory notebooks at UNSOM department of Surgery Research Laboratory.

11. "Corrective and Preventive Actions (CAPA) – Provide a procedure and system by which CAPA can be initiated, documented, and completed for UNSOM department of Surgery Research Laboratory.

12. "Change Control" – Procedure for initiation, review, approval, implementation, and documentation of changes made to Specifications, Procedures, Protocols, Validations and any GMP documentation or equipment that may impact a regulatory submission or the identity, strength, quality and purity of a product at UNSOM department of Surgery Research Laboratory.

13. "Investigating Out of Specification (OOS) Test Results" – Procedure for providing guidance for investigating OOS GMP test results at UNSOM department of Surgery Research Laboratory.

14. "Records Retention Policy" – Defines UNSOM department of Surgery Research Laboratory record retention policy for production, control and distribution of documents and reports.

15. "Qualification of Vendors & Contract Facilities" – Provide a standardized procedure, requirements and responsibilities for qualification and continued certification of vendors and contract facilities at UNSOM department of Surgery Research Laboratory.

16. "Internal Audits" – Provide a system of self-assessment through randomly scheduled internal audits at regular intervals at UNSOM department of Surgery Research Laboratory.

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23. "Personal Hygiene" – Provide a procedure and instruction in personal hygiene for all UNSOM personnel subject to Good Manufacturing Practices (GMP).

24. "Central Documentation" – Procedure to determine which documents should be retained in Central Documentation and the retention period for various types of documents.

Teleconference with Military Experts

During Y1Q3 UNSOM and Rocky Research held two teleconferences with military experts and answered questions regarding Commercial off-the-shelf (COTS) blankets to be tested, the user interface of the device, temperature sensors, typical use with regards to military applications, and the control algorithm. Additional information was requested by the working group during Y1Q4 regarding a diagram illustrating the interaction of the body temperature conditioning system with the patient and clinical scenarios in which this system could be utilized.
See Appendix A: Notes from May 17, 2012 Teleconference with University of Nevada, Reno Portable Body Temperature Conditioner

Task 2: Prototype Fabrication (Months 7-12). **In Progress**

2a. Breadboard design and Fabrication

The breadboard design is very similar to the prototype design as shown in figure1. The exception is that the breadboard is designed such that components can be changed as needed with ease. Since the component changes requires the connections not to be all soldered and as such quick connect and disconnects are used in the breadboard where in the packaged prototype these will be replaced with continous tubing and solder joints.

Figures 7-9 show the completed benchtop with the Data acquisition system. The instrumentations measured all relevant temperature and pressure statepoints in addition to cooling capacity and power consumtion. All the data are logged for further analysis.
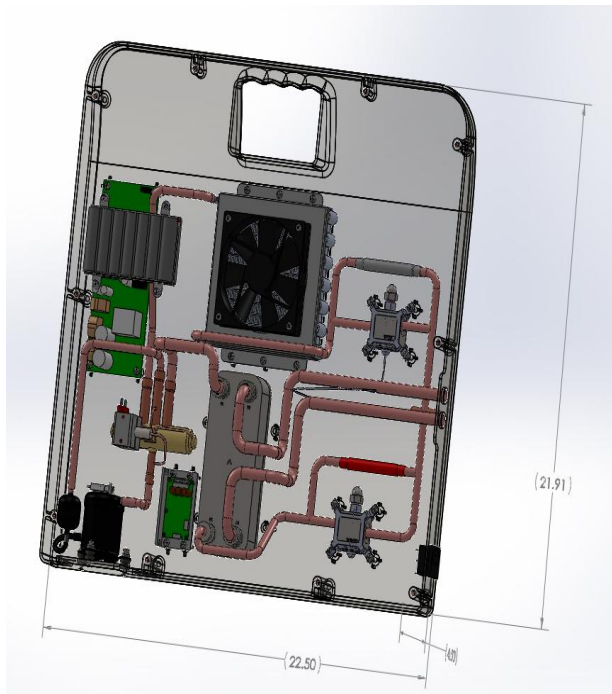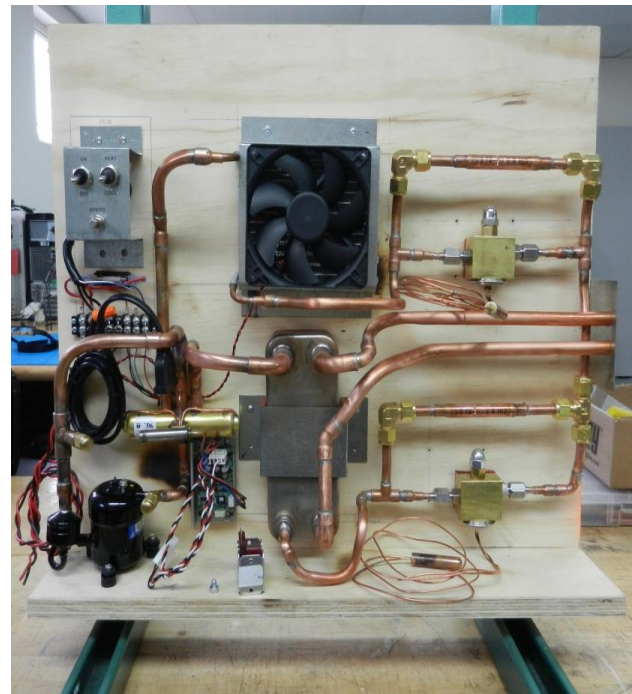
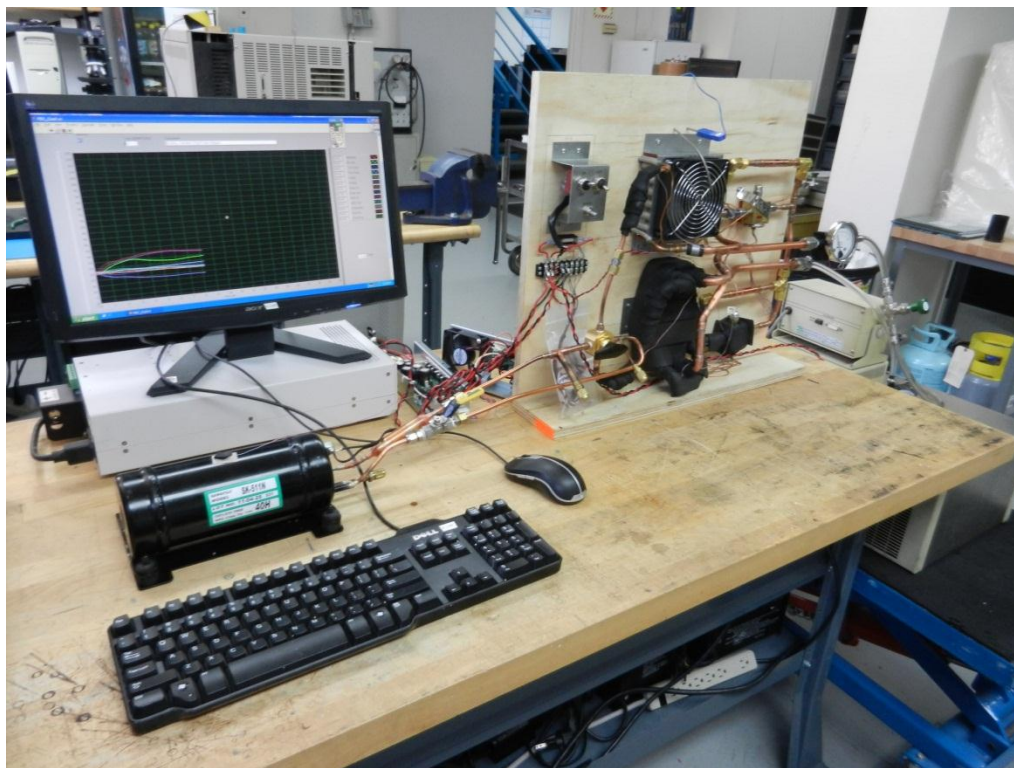Figure 7. 3-D Solid-model of Prototype design

Figure 8. Benchtop prototype

Figure 9. Benchtop with DAQ

2b. Breadboard Test Results

Compressor selection was a primary focus of breadboard testing. Complete test matrices have been constructed and evaluated for each of the compressors under consideration. The test matrices are extensive because each compressor was analyzed at varying compressor speeds under different heating and cooling conditions. Tables 3, 4, and 5 depict the test matrices for the Aspen, Danfoss, and Sawafuji compressors, respectively. Cooling modes were tested for bath temperatures of 20 °C, 10 °C, and 5 °C while heating performance was evaluated with bath temperatures of 42 °C and 40 °C. Voltage was maintained constant for each test at 25.2v. The coefficient of performance (COP) was calculated for each compressor under each heating and cooling assessment to evaluate overall compressor performance. The performance of each compressor was then compared and contrasted in terms of capacity, efficiency, and feasibility while considering size and weight parameters. It is important to distinguish that all compressor testing was performed open loop, with a bath simulating the load. The selected compressor will have to be re-analyzed with loading from the thermal manikin before being implemented in the final prototype.

Table 3. Complete Test matrix for Aspen Compressor

		Aspen Compressor Test Matrix		0.2 A Compressor cooling fan							
		1180-PBTC		0.4 A Condensor fan and H_2O pump combined							
Control Voltage:	2.13										
	RPM [3000]										
		H_2O Out [°C]	$\Delta T\ H_2O$ [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP	
Bath Temperature [20°C]	26June12 C7	15	5	25.2	5.2	0.015770881	4.182	131.04	329.7691143	2.516553070	
Bath Temperature [10°C]	27June12 C4	6.5	3.5	25.2	4.0	0.015770881	4.192	100.8	231.3903608	2.295539294	
Bath Temperature [5°C]	27June12 C8	3.5	1.5	25.2	3.8	0.015770881	4.203	95.76	99.42751703	1.038299050	
Bath Temperature [42°C]	27June12 H1	45.0	3.0	25.2	4.9	0.015770881	4.179	123.48	197.7195307	1.601227168	
Bath Temperature [40°C]	28June12 H5	43.0	3.0	25.2	4.7	0.015770881	4.1785	118.44	197.6958743	1.669164761	
Control Voltage:	2.8										
	RPM [4000]										
		H_2O Out [°C]	$\Delta T\ H_2O$ [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP	
Bath Temperature [20°C]	26June12 C8	14	6	25.2	6.1	0.015770881	4.182	153.72	395.7229372	2.574310026	
Bath Temperature [10°C]	27June12 C5	6	4	25.2	4.8	0.015770881	4.192	120.96	264.4461267	2.186227899	
Bath Temperature [5°C]	27June12 C9	3	2	25.2	4.6	0.015770881	4.203	115.92	132.5700227	1.143633736	
Bath Temperature [42°C]	27June12 H2	45.0	3.0	25.2	5.4	0.015770881	4.179	136.08	197.7195307	1.452965393	
Bath Temperature [40°C]	28June12 H6	43.0	3.0	25.2	5.1	0.015770881	4.1785	128.52	197.6958743	1.538249878	
Control Voltage:	3.54										
	RPM [5000]										
		H_2O Out [°C]	$\Delta T\ H_2O$ [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP	
Bath Temperature [20°C]	27June12 C2	14	6	25.2	6.8	0.015770881	4.182	171.36	395.7229372	2.309307523	
Bath Temperature [10°C]	27June12 C6	6	4	25.2	5.7	0.015770881	4.192	143.64	264.4461267	1.841034020	
Bath Temperature [5°C]	27June12 C10	2	3	25.2	5.5	0.015770881	4.203	138.6	198.8550341	1.434740506	
Bath Temperature [42°C]	27June12 H1	45.0	3.0	25.2	5.6	0.015770881	4.179	141.12	197.7195307	1.401073772	
Bath Temperature [40°C]	28June12 H5	43.5	3.5	25.2	5.6	0.015770881	4.1785	141.12	230.6451867	1.634390496	
Control Voltage:	4.1										
	RPM [6000]										
		H_2O Out [°C]	$\Delta T\ H_2O$ [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP	
Bath Temperature [20°C]	27June12 C3	14	6.0	25.2	8.0	0.015770881	4.182	201.6	395.7229372	1.962911395	
Bath Temperature [10°C]	27June12 C7	5.5	4.5	25.2	7.7	0.015770881	4.192	194	297.5018925	1.533198786	
Bath Temperature [5°C]	27June12 C11	2	3	25.2	6.1	0.015770881	4.203	153.7	198.8550341	1.293618489	
Bath Temperature [42°C]	28June12 H4	46.0	4.0	25.2	6.5	0.015770881	4.179	163.8	263.6260409	1.609438589	
Bath Temperature [40°C]	28June12 H8	44.0	4.0	25.2	6.2	0.015770881	4.1785	156.2	263.5944991	1.687112770	

Table 4. Complete Test matrix for Danfoss Compressor

	Danfoss Compressor Test Matrix		0.2 A Compressor cooling fan						
	1180-PBTC		0.4 A Condensor fan and H_2O pump combined						
Control Resistance: Ohms	0								
	RPM [2000]								
		H$_2$O Out [°C]	ΔT H$_2$O [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP
Bath Temperature [20°C]	02July12 C1	17	3	25.2	2.3	0.015770881	4.182	57.96	197.8614686	3.413758947
Bath Temperature [10°C]	02July12 C5	8	2.0	25.2	2.2	0.015770881	4.192	55.44	132.2230633	2.384975890
Bath Temperature [5°C]	02July12 C9	4	1	25.2	2.1	0.015770881	4.203	52.92	66.28501136	1.252551235
Bath Temperature [42°C]	03July12 H1	43.0	1.0	25.2	2.6	0.015770881	4.179	65.52	65.90651022	1.005899118
Bath Temperature [40°C]	03July12 H5	41.5	1.5	25.2	2.5	0.015770881	4.1785	63	98.84793717	1.569014876
Control Resistance: Ohms	277									
	RPM [2500]									
		H$_2$O Out [°C]	ΔT H$_2$O [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP
Bath Temperature [20°C]	02July12 C2	17	3	25.2	2.9	0.015770881	4.182	73.08	197.8614686	2.707463993
Bath Temperature [10°C]	02July12 C6	7.5	2.5	25.2	2.7	0.015770881	4.192	68.04	165.2788292	2.429142110
Bath Temperature [5°C]	02July12 C10	3.5	1.5	25.2	2.6	0.015770881	4.203	65.52	99.42751703	1.517513996
Bath Temperature [42°C]	03July12 H2	43.0	1.0	25.2	3.1	0.015770881	4.179	78.12	65.90651022	0.843657325
Bath Temperature [40°C]	03July12 H6	42.0	2.0	25.2	3.0	0.015770881	4.1785	75.6	131.7972496	1.743349862
Control Resistance: Ohms	692									
	RPM [3000]									
		H$_2$O Out [°C]	ΔT H$_2$O [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP
Bath Temperature [20°C]	02July12 C3	17	3	25.2	3.5	0.015770881	4.182	88.2	197.8614686	2.243327308
Bath Temperature [10°C]	02July12 C6	7	3	25.2	3.3	0.015770881	4.192	83.16	198.3345950	2.384975890
Bath Temperature [5°C]	02July12 C10	4	1.5	25.2	3.1	0.015770881	4.203	78.12	99.42751703	1.272753674
Bath Temperature [42°C]	03July12 H3	43.0	1.0	25.2	3.8	0.015770881	4.179	95.76	65.90651022	0.688246765
Bath Temperature [40°C]	03July12 H7	42.5	2.5	25.2	3.7	0.015770881	4.1785	93.24	164.7465619	1.766908644
Control Resistance: Ohms	1523									
	RPM [3500]									
		H$_2$O Out [°C]	ΔT H$_2$O [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP
Bath Temperature [20°C]	02July12 C4	16.5	3.5	25.2	4.2	0.015770881	4.182	105.84	230.83838	2.181012661
Bath Temperature [10°C]	02July12 C8	7	3	25.2	3.9	0.015770881	4.192	98.28	198.34595	2.018056522
Bath Temperature [5°C]	03July12 C12	3	2	25.2	3.8	0.015770881	4.203	95.76	132.5700227	1.384398733
Bath Temperature [42°C]	03July12 H4	44.0	2.0	25.2	4.3	0.015770881	4.179	108.36	131.813020	1.216436143
Bath Temperature [40°C]	03July12 H8	43.0	3.0	25.2	4.4	0.015770881	4.1785	110.88	197.6958743	1.782971450

Table 5. Complete Test matrix for Sawafuji Compressor

	Sawafuji Compressor Test Matrix		0.2 A Compressor cooling fan						
	1180-PBTC		0.4 A Condensor fan and H_2O pump combined						
Cooling Mode										
		H$_2$O Out [°C]	ΔT H$_2$O [°C]	V [V]	I [A]	m(dot) [kg/s]	Cp [kJ/kg -°C]	P [W]	Q [W]	COP
Bath Temperature [20°C]	09July12 C3	19	1	25.2	2.2	0.015770881	4.182	55.44	65.95382286	1.189643270
Bath Temperature [10°C]	09July12 C1	9.5	0.5	25.2	2.1	0.015770881	4.192	52.92	33.05576583	0.624636543
Bath Temperature [5°C]	09July12 C2	4.8	0.2	25.2	2.0	0.015770881	4.203	50.4	13.25700227	0.263035759
Heating Mode										
Bath Temperature [42°C]	10July12 H2	41.5	0.5	25.2	2.3	0.015770881	4.179	58.0	32.95325511	0.568551675
Bath Temperature [40°C]	10July12 H1	39.5	0.5	25.2	2.3	0.015770881	4.1785	58.0	32.94931239	0.568483651
	*No Heating									
	*No Heating									

Upon completion of the compressor test matrices several observations were realized. The Sawafuji swing motor compressor did not allow for the variance of motor speed. Resultantly, the compressor demonstrated poor performance as depicted by the COP in table 5, particularly for the heating mode tests. Consequently, the Sawafuji compressor was immediately eliminated as a viable option for prototype fabrication.

Contrasting the Aspen compressor with the Danfoss compressor it was observed that the COP of each was comparable. Depending on motor speed, the general trend was that the Aspen performed slightly superior in terms of heating effectiveness and the Danfoss slightly better in terms of cooling efficiency. Identification of the most suitable compressor for continuing with system prototyping was subsequently determined by the size and weight of all required components. The Aspen compressor has an approximate volume of $14.8in^3$ and weighs approximately 1.32lb. The Danfoss compressor measures approximately $221.2in^3$ and weighs approximately 10.03lb. Although the Aspen compressor is much smaller in size and weight than the Danfoss it also draws more current. Subsequently, a larger battery pack is required for similar operational length conditions. Therefore, in order to properly analyze size and weight comparisons between the two, compressor battery sizing and evaluation was implemented.

Polymer Li-Ion batteries with high energy density were selected for battery pack selection and analysis. Battery packs with polymer Li-Ion cells of 3.7v and varying nominal capacities were evaluated. Since 7 cells were required for both the Aspen and Danfoss compressors, cell size and weight was only varied by the capacity required for each compressor. It was found that little weight and size, in comparison to the compressors themselves, was eliminated by employing a battery pack with the less capacity required to power the Danfoss compressor for the same period of time as the Aspen compressor. Therefore, overall system component size was drastically smaller with utilization of the Aspen compressor in comparison to the Danfoss compressor. With similar performance characteristics, the Aspen compressor has been selected for utilization in progressing forward with the portable body temperature conditioner prototype. The compressor still needs to be analyzed on the breadboard with loading provided by the thermal manikin before being selected for final prototype fabrication.

The battery selected for the breadboard unit is a 25.9v and 12.6Ah (326.34Wh) Li-Ion polymer battery pack. The dimensions of the pack are 7.1" (181mm) x 3.0" (77mm) x 3.3" (85mm) and the pack weighs 3.5lb (1585g). The pack was tested on the breadboard in both heating and cooling modes with the Aspen compressor operating at maximum speed. Some Li-ion polymer batteries demonstrate a de-rating at lower operating temperatures (60% at -20 °C). With the 12.6Ah even if the battery pack is de-rated to 60% at -20 °C, it is still within the acceptable operating parameters for the Aspen compressor functioning at maximum speed. For the heating test the battery was placed in a freezer at -20 °C in order to emulate any de-rating effects. The result of both the cooling and heating test are presented in figures 10 and 11, respectively.
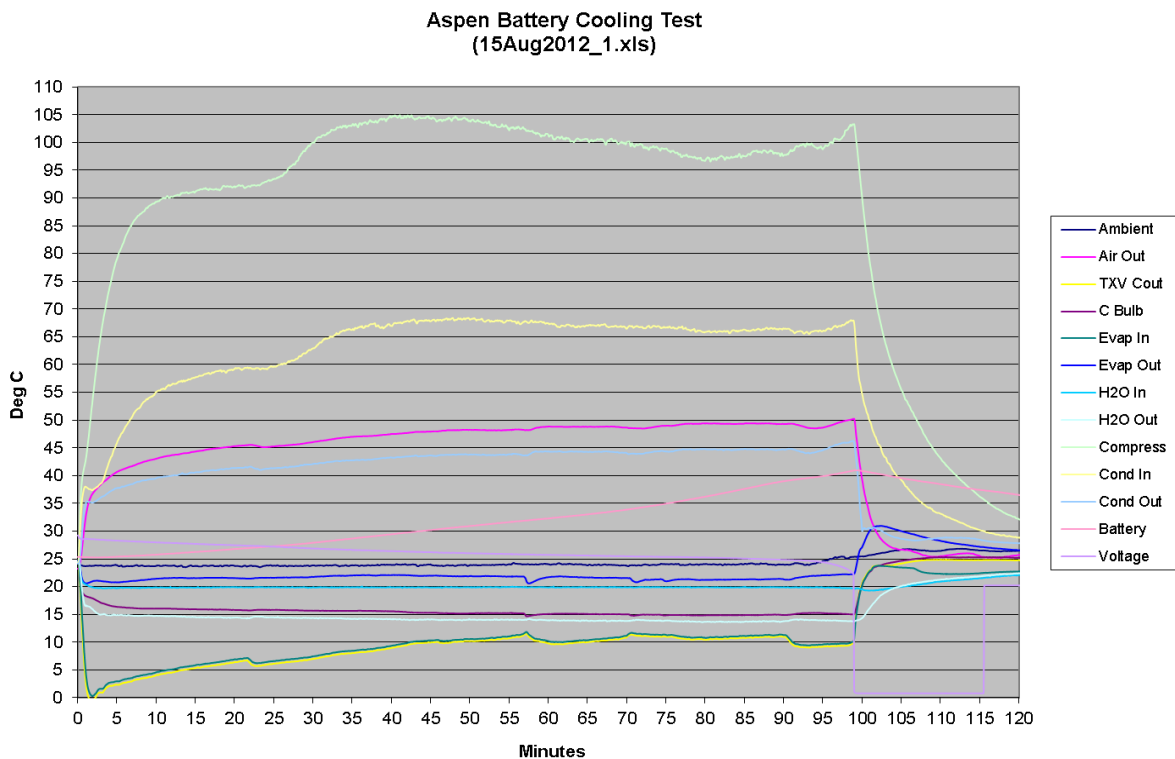

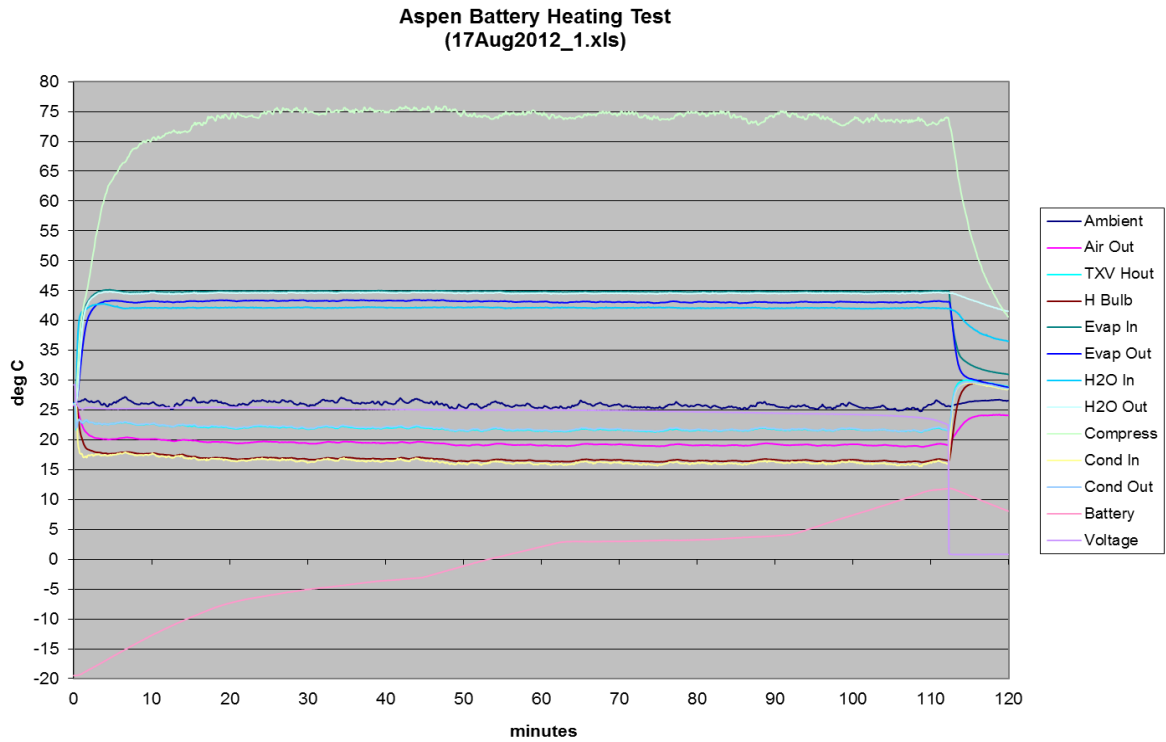Figure 10. Battery pack cooling test with Aspen compressor

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Figure 11. Battery pack heating test with Aspen compressor

As can be observed, the battery pack was able to adequately supply power to all of the breadboard components for 100 minutes in cooling mode and 110 minutes in heating mode. Consequently, the battery pack was verified as a sufficient selection for progressing forward with the portable body temperature conditioner prototype. A battery charger and power supply have also been selected for the unit. The smart charger has a standard charging rate of 6.0A, capable of recharging the entire battery pack in approximately 3.15 hours. The power supply is a high efficiency, low profile, component with full digital control and high peak loading capability. Both components have been tested on the breadboard. The charger and power supply are packaged separately from the portable body temperature conditioner unit as a detachable external component. Such an approach allows for the unit to retain its minimalistic characteristics in terms of weight and size. Figure 12 presents a drawing of the unit along with the packaged external power supply and charger. The dimensions have been specified on the drawing in inches.
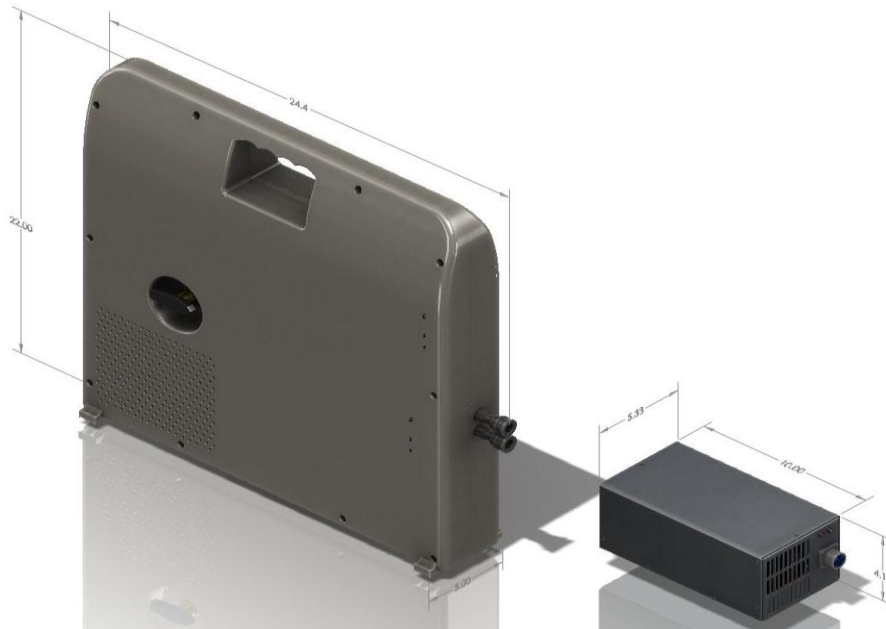

Figure 12. Prototype design with externally packaged power supply and charger unit

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Two pumps have been investigated for utilization in the portable body temperature conditioner unit. A 24v centrifugal pump with dimensions of 3.75" L x 3" W x 3" H and a maximum flow rate of 1.1gpm has been initially selected. The other pump under consideration was a small micro pump with 0.57" D x 2.5" L. Although the micro pump was optimal in terms of size, after extensive testing, it was concluded that the pump did not provide adequate capability in maintaining flow rates. Furthermore, the micro pump was relatively noisy and raised concerns in terms of reliability. Open loop testing of the selected centrifugal pump through the entire system loop, including hyper-hypothermia blanket, revealed the pump was able to maintain a flow rate of approximately 0.5gpm with 1ft of pressure head.

A hyper-hypothermia blanket has been selected for utilization in evaluating performance of the portable body temperature conditioner unit. The blanket has been obtained along with the required connection hose. The blanket utilized for system performance analysis is a Cincinnati Sub-Zero adult sized Maxi-Therm$^{®}$ blanket measuring 60" L x 24" W. Proper quick connect hydraulic couplings have been acquired and fitted to the plumbing of the breadboard unit to allow connection of the portable conditioner to the blanket via the 9′ connection hose. Flow has been analyzed through the blanket and weight measurements of full and empty blankets, as well as connection hoses, have been taken in order to quantify water content. It was found that at ambient conditions (25 °C) the blanket and hose contain approximately 15.6L (95in^3) of water during operation, a crucial quantification in designing for system filling procedures.

2c. Prototype Fabrication

The prototype design for the portable body temperature conditioner has been refined based on the results of breadboard component testing. A drawing of the new design, with all of the currently identified components, is presented in figure 13. The drawing also depicts necessary mounting hardware. Prototype fabrication has not yet begun since the breadboard still needs to be evaluated with a load provided by the thermal manikin. Logically, comprehensive testing on the breadboard utilizing the thermal manikin should be implemented before prototype fabrication. Such an approach allows for the components to be thoroughly evaluated before final selection. The portable body temperature conditioner unit is depicted in figure 14 along with the external power supply, connection hose, thermal manikin, and hyper-hypothermia blanket. The orientation of the drawing in figure 14 is such that the thermal manikin is lying on its back. Once the thermal manikin is obtained completion of breadboard testing will ensue, and final component selection for prototype fabrications will be implemented.
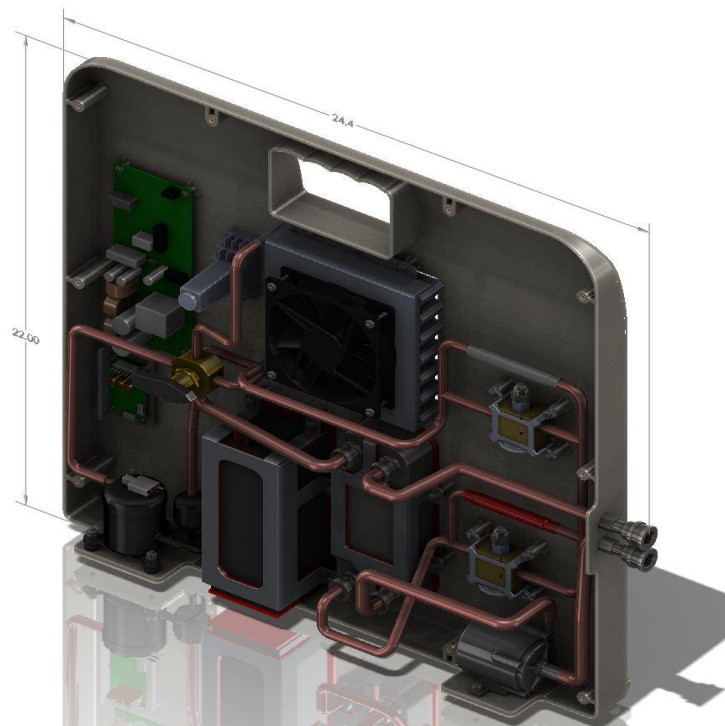

Figure 13. Internal prototype design perspective with intended selected components
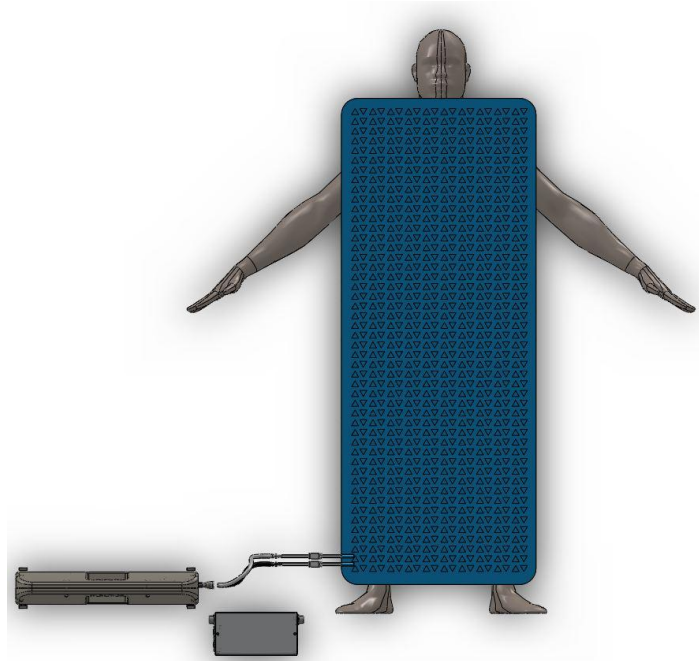
20

Figure 14. Aerial view of conditioner, connection hose, power supply, blanket, and thermal manikin

Task 3: Prototype Testing (Months 12-24). **Yet to start** (Task 3 set to begin upon completion of Task 2, within the first quarter of year 2)

  a. Functional testing. **Yet to start**

  b. Performance testing (manual control). **Yet to start**

  c. Control logic testing. **Yet to start**

  d. Modifications as necessary and retest. **Yet to start**

Task 4: Patient Load Simulation Testing (Months 9 – 24). **In Progress**

Write test and validation methods

UNSOM has begun determining standard testing metrics to be used during the patient simulation testing. These metrics include; temperature limits of the convective fluid, allowable patient core temperature range, ranges of hypo-hyperthermia, and temperature/heat flux conditions.

Receive and training on thermal manikin/software

The thermal manikin "Newton" was purchased from Measurement Technology Northwest (MTNW), which is a Seattle based company specializing in the manufacture of thermal manikins and associated accessories. The manikin was originally scheduled to be delivered at the end of August; however there was a slight delay in fabrication by MTNW. Fabrication of the manikin was completed and shipped from MTNW on 07-Sep-2012. UNSOM received the thermal manikin and associated accessories on 11-Sep-2012.

Training personnel from Measurement Technology Northwest (MTNW) were scheduled to come for two days from September 26-27, 2012. Included with the training session, MTNW personnel are expected to assemble and test the thermal manikin "Newton" and the associated accessories. Additionally, MTNW personnel are going to train UNSOM and pertinent Rocky Research staff on the general use and maintenance of the thermal manikin "Newton".

Validation of the thermal manikin

Measurement technology Northwest will perform parts of the validation procedures for installation qualification (IQ) and operational qualification (OQ) when they come for the assembly-training session for the thermal manikin. Additionally, MTNW will train UNSOM and Rocky Research personnel on how to do performance checks/calibration during routine maintenance, which will encompass performance qualification (PQ).

KEY RESEARCH ACCOMPLISHMENTS:

The Following were accomplished in the past year:

- System Design: The vapor compression system used in the prototype was modeled, performance was predicted and components selected.
- Breadboard Prototype Fabrication: The prototype was assembled on a laboratory breadboard. The size and dimension of the overall breadboard is kept exactly the same as the final prototype.
- Breadboard Prototype testing: The prototype testing was completed and components were selected based on the performance results.
- Prototype Drawings: The drawings for the final prototype were completed and refined during testing. These engineering drawings will be used for future fabrication and cost analysis.
- The system performance on cooling and heating capacity and COP are shown in Table 3. The cooling capacity was measure to be between 200 to 400 Watts at COPs of greater than 1.5. The heating Performance was between 200 to 300 Watts at COPs of greater than 1.7.
- The prototype was successfully tested using DC generated from high power density Lithium-Polymer batteries and 110VAC power.
- Patient Simulation Testing: The thermal manikin was purchased and received from Measurement Technology Northwest on 11-Sep-2012. Also, a training-installation session was scheduled for September 26-27, 2012 to introduce UNSOM and select Rocky Research personnel to the general use and maintenance of the thermal manikin and associated software.
- Implementing QSR: Currently, 24 Standard Operating Procedures (SOP's) have been implemented for UNSOM's quality systems. Rocky Research began implementing SOP's in March 2012 and continues to implement approximately 2 – 5 SOP's per quarter. UNSOM continues to work with a FDA consultant as part of QSR compliance.

REPORTABLE OUTCOMES:

Currently, the project is still in the design/fabrication phase of the prototype and testing of the device has not yet begun. As such, no abstracts, presentations, publications or other equivalent reportable outcomes have been produced from this research at this time.

CONCLUSION:

The prototype breadboard for portable body temperature conditioner has been successfully designed, fabricated, and tested. The test results show that the prototype meets the overall capacity and efficiency requirements. The prototype was further tested using both AC and DC power sources thus demonstrating the power versatility feature. The DC power operation lasted more than 1 hour exceeding the initial design goal. Also, a water-circulating blanket was purchased and integrated with the prototype. A custom thermal-

manikin was purchased and received from Measurement Technology Northwest on 11-September-2012. Additionally, a training-installation session was scheduled with MTNW for the 26-27-Sep-2012. Installation and operation qualification will be completed during the scheduled training session with MTNW as part of the validation procedure. Further testing of the prototype, water-circulating blanket, and the thermal-manikin is required to reveal necessary refinements in the prototype. Once these refinements are made a complete prototype will then be assembled and tested. Additionally, quality system regulations are currently being implemented by both UNSOM and Rocky Research as part of a working goal toward FDA medical device clearance and 510(k) submission.

Defense medical installations require efficient and reliable equipment for the thermoregulation of either injured or ill patients. However, effective methods for warming/cooling injured patients during medical evacuations in the absence of a reliable power source are currently unavailable. The current research will yield a portable, reliable, intuitive device that will effectively maintain normal core body temperature during transport between various levels of combat casualty care. Similarly, the portable body temperature conditioner will also translate to civilian use as an essential tool for Emergency Medical Service (EMS) crews in response to emergency situations within the general public.

AWARD PARTICIPANTS:

The number of individuals participating on this project and receiving salary support from this USAMRAA award during this reporting period is listed below.

Organization	Number of Supported Staff
UNSOM	3
Med-School Associates South	2
Rocky Research	5
Total Number Supported Staff	**10**

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APPENDICES / SUPPORTING DATA:

Appendix A:

Notes from May 17, 2012 Teleconference with University of Nevada, Reno
Portable Body Temperature Conditioner

General Questions

The main goal in the development of the portable body temperature conditioner is core temperature maintenance as to prevent further temperature loss. It may be difficult to raise a patient's core temperature in the field due to non-ideal conditions and the patient's injuries. The advantages of the proposed system is that it will provide sufficient heating and cooling power to maintain normothermia under typical conditions encountered in the field and during air transport.

1. Clinical utility in austere environments where ice packs are not available.
   - To promote use in austere environments, the device will be lightweight, of minimal size, and battery operated allowing for maximum portability.

2. Does design address MilSpecs and when will you test device for meeting MilSpecs?
   - **Phase I Technical Objectives**

   The major technical objectives of the proposed project are to design, develop, fabricate, and test a portable body temperature conditioner subject to extreme ambient conditions to determine performance and cost. In order to reach realistic results a compressor breadboard suitable to measure energy consumption and evaluate the feasibility and practicality of the concept will be fabricated and used. The data generated in the compressor breadboard will be used in the design. Based on the compressor and heat exchanger selection a 3-D solid model of the system will be generated using SolidWorks. A prototype will then be fabricated and tested with and without simulated patient body heat loads. Sub-objectives are:

   1. The development of an analytical model of the system
   2. The design of the prototype
   3. SolidWorks 3-D modeling and drawings
   4. The fabrication of the prototype
   5. Testing of the prototype on the workbench
   6. Testing of the prototype with the patient simulated load
   7. Preliminary cost analysis
   8. Begin implementing design and quality regulatory controls required by Food and Drug Administration (FDA)

   - **Military Standards**

   The system will be designed to operate in harsh military environments including airborne, shipboard, and ground mobile conditions. The device will be designed to meet military standards in current phase but not tested for meeting military standards until fabrication of the prototype has been completed. This is scheduled to occur in phase 3 of the project. The specific Mil-Standards that the system will be designed to pass in the upcoming phase are:

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Environmental
- MIL-STD-810G-507.4 HUMIDITY
- MIL-STD-810G-509.4 SALT/FOG
- MIL-STD-810G-510.4SAND/DUST
- MIL-STD-810G-500.4 LOW PRESSURE(ALTITUDE) PROCEDURE II
- MIL-STD-810G-501.4 HIGH TEMPERATURE PROCEDURE I
- MIL-STD-810G-501.4 HIGH TEMPERATURE PROCEDURE II
- MIL-STD-810G-502.4 LOW TEMPERATURE PROCEDURE II
- MIL-STD-810G-514.5 VIBRATION
- MIL-STD-810G-516.5MECHANICAL SHOCK, PROCEDURE

EMI (The following Mil-Standards apply to Air –worthiness in addition to mobile systems on the ground)
- MIL-STD 461E,FCE 102 CONDUCTED EMISSIONS, POWER LEADS
- MIL-STD 461E,FCS 10 CONDUCTED SUSCEPTIBILITY, POWER LEADS
- MIL-STD 461E,FRE 102 RADIATED EMISSIONS
- MIL-STD 461E,FRS 103RADIATED SUSCEPTIBILITY

3. How does system interact with casualty? (Provide diagram of the whole system with casualty)

- The device will be able to interface with a typical core temperature measuring probe, allowing for a direct feedback control system based on the patient's core body temperature. In automatic or gradient temperature mode, the device will provide heating or cooling based on the patient's current core temperature, circulating the appropriate temperature fluid through the convective/conductive blanket. A simple diagram of the interface between the patient and the temperature conditioning device is provided in figure 1. The body temperature conditioning system is connected to the convective blanket with an inlet and exit flow setup. This allows the heated or cooled convective fluid to flow into the blanket, circulate, and then exit back into the temperature conditioning device. The user interface is a generalized schematic and is planned to incorporate a user interface similar to commercial conditioning blanket systems. A simple flow chart describing the interaction between the patient and temperature conditioning device is in gradient or automatic mode is provided in figure 2.

  In just about every scenario where this device would be used the patient will need to be intubated and sedated, as the systems primary function is to maintain core body temperature or warm/cool the patient as part of a resuscitative effort during transport to improve the patient's outcome.

  In a cardiac arrest scenario where the idea is to cool the patient and prevent brain injury the patient will need to be intubated and sedated to tolerate cooling. Most patients put into iatrogenic hypothermia will shiver, experience pain, and on a whole be really uncomfortable. If they are sufficiently obtunded to require this therapy then they almost certainly will require intubation. Cooling of a patient is not recommended unless the patient requires intubation and an invasive temperature monitoring probe is required.

- **Clinical Scenario**

  A 24 year old male suffers blast wounds to the right upper extremity and torso with 10% total body surface area burns to the chest. The ambient temperature is 22° C. A first responder arrives and upon removing the burned clothing and exposing the areas of injury, severe mangling of the extremity is noted. The patient is moved to a safe location where it is determined his airway is patent, he is breathing without issues and he has palpable pulses in all extremities save the mangled arm. The transport team arrives and IV access is placed in the unaffected limb and room temperature fluids are initiated. The patient is tachycardic and anxious, his blood pressure is normal, skin temperature is 36.0° C. The patient complains of severe abdominal pain and intra-abdominal injury is suspected.

  In this scenario the patient is already in the early stages of shock. He is also mildly hypothermic. In a scenario such as this where the ambient temperature is 22° C, the patient is burned, and the patient has had significant blood loss - the patient warmer would be applied with the arrival of transport utilizing a skin temperature probe. In this situation, the body temperature conditioning device is primarily being used for body temperature maintenance, as to prevent any further heat loss. This, in addition to resuscitation would prevent worsening of the

hypothermia and subsequent coagulopathy. An invasive core temperature monitor could be placed should the patient require intubation or additional invasive monitoring. In burned patients heat loss can occur quickly. Lastly, this patient may require urgent operative intervention. Acidosis and coagulopathy can be prevented by addressing the issue of heat loss via blanket technology rather than "playing catch-up" in the OR.
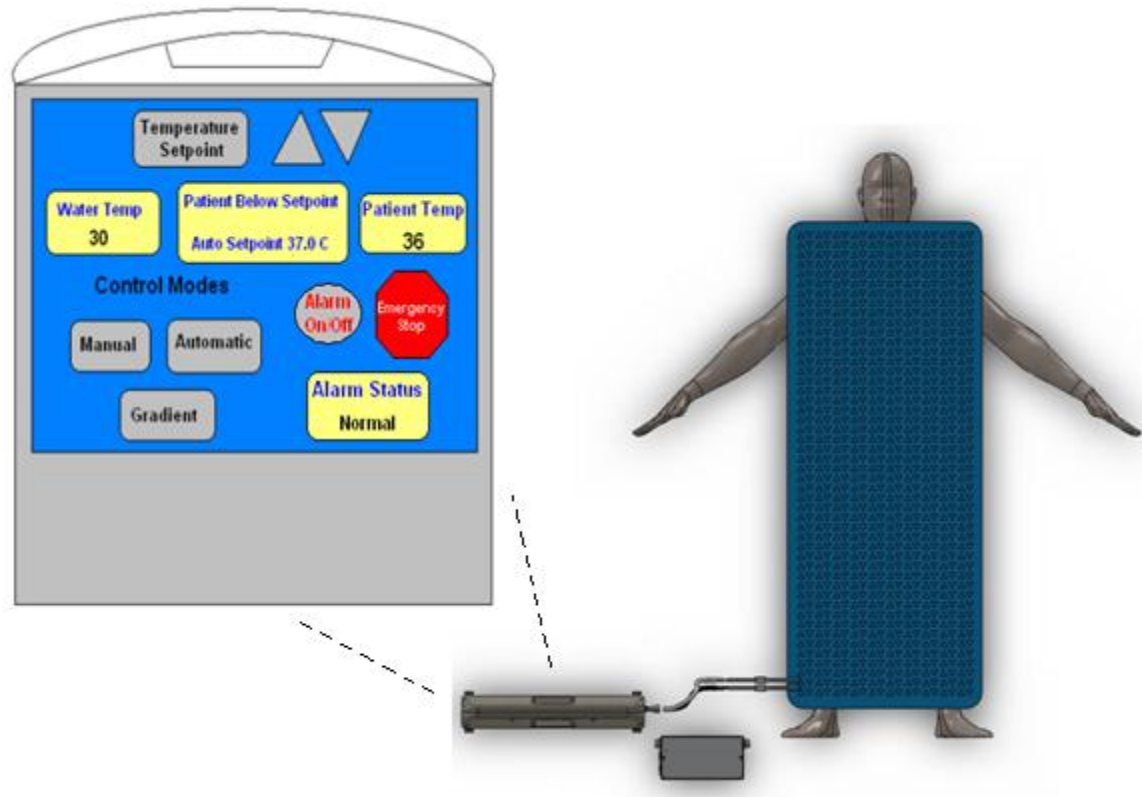

Figure 1. Diagram of body temperature conditioning system interaction with patient.

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                    │   Select    │
                    │ Manual/Auto │
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                Auto ╱               ╲ Manual
          ┌──────────────┐      ┌──────────────┐
          │ Gradient or  │      │ Temperature  │
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         YES ╱      ╲ NO                │
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   │ Gradient  │ │ Temperature  │  │   Temperature    │
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Gradient or AUTO — YES: Gradient Set Point / NO: Temperature set point

Temperature Measurement

Cooling/Heating Variable Speed Controls

Check for Alarms

Report/ Take Action: Stop

Continue Temp or gradient set point/ measurement feedback

Temperature Set Point

Temperature Measurement

Cooling/Heating Variable Speed Controls

Check for Alarms

Report/ Take Action: Stop

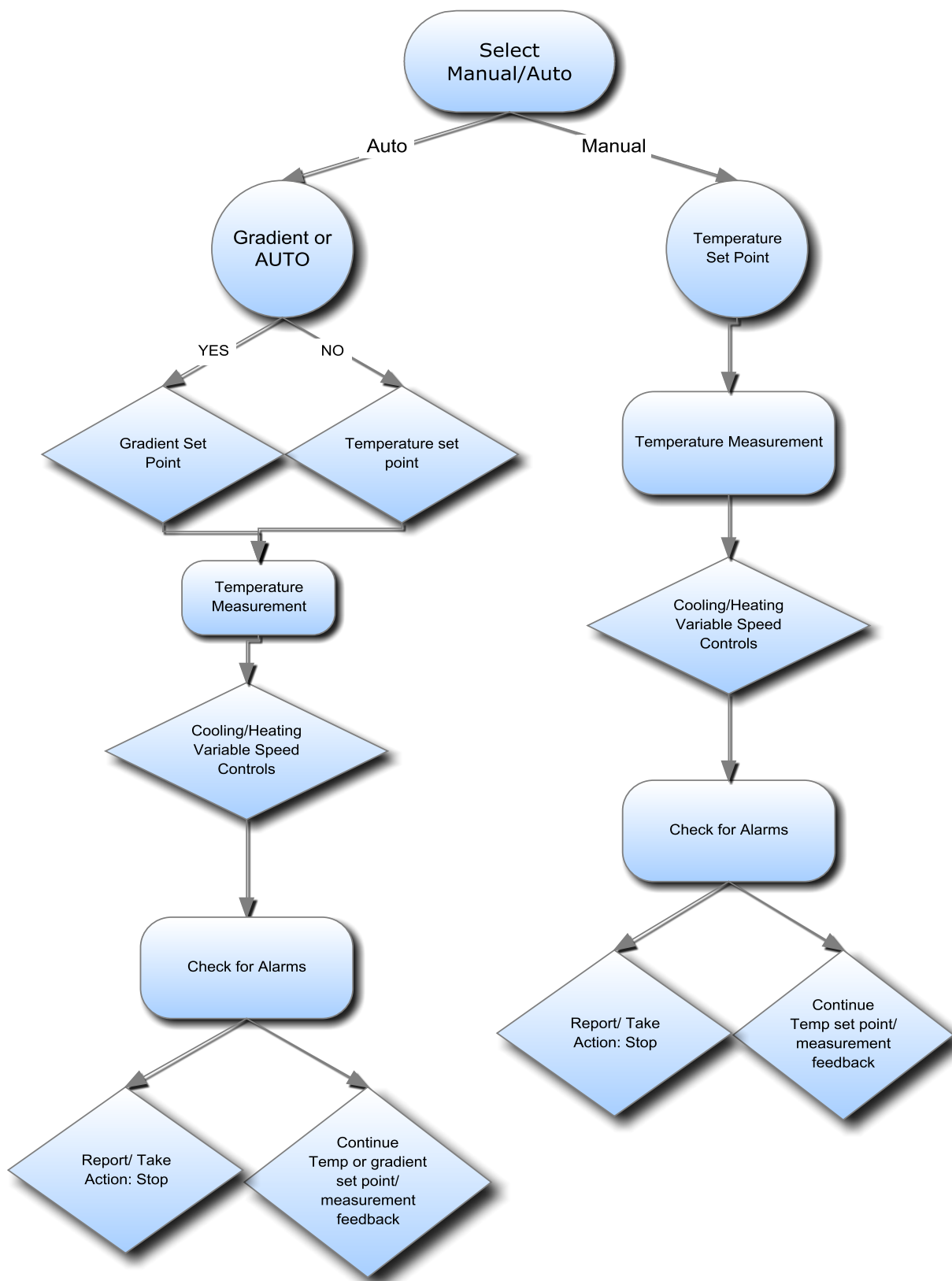Continue Temp set point/ measurement feedback

Figure 2. Simple flow chart describing the interface between patient and temperature conditioning device.

4. How are adjustments made to not allow patient to get too hot or too cold?
   - With respect to patient safety and ease of operation, the device will have several safety applications built in. To prevent the patient from being over heated or cooled, the device will have upper and lower limits of temperature, control systems, automatic shut-off when the temperature exceeds set points, and an alarm system to notify the operator of dangerous temperature situations.

5. Can the system be used by a medic or nurse and who will use this device?
   - The device will provide a user friendly interface displaying the following essential patient care data; patient core temperature, water temperature, and the system status which indicates the temperature set point and any necessary corrections to be made by the operator. The system will be designed with intuitive controls to promote ease of use with medics up to physicians. The system will have an automatic and manual control option for basic temperature management use and a more controlled use by physicians. The portability of the device will allow its use in the field, during airborne evacuation, and within a traditional hospital setting.

6. What is your business plan?
   - Working with medical device manufacturers. We are currently having discussions with Cincinnati Sub-Zero (CSZ) as a possible consultant on this project. CSZ is a company in the medical temperature management market. This is an established company with various products related to Hyper-Hypothermia systems.

7. How much will it cost?
   - Rocky Research will complete a cost estimate at the end of the current phase when the first prototype is fabricated and tested. At this time there are too many unknown factors associated with parts, blankets, and the overall fabrication of the prototype to estimate the cost of the device.

Blanket questions

1. Clarification on blanket(s) to be tested.
   - CSZ manufactures blankets for hyper-hypothermia systems. If CSZ becomes a consultant on this project then we can test their blankets on the device. If not, then we will evaluate other commercial off-the-shelf (COTS) blankets.

2. Will the blanket be sold as part of the device?
   - The blanket may be sold as part of the device, but should also be available as a standalone product. Single use or multiple use blankets may be sold, depending on what would be most convenient for the military.

3. Will recommendations be made?
   - Based on patient simulation testing, recommendations will be made as to the various types of blankets to be used with the system. (ie. Pads, whole body blankets, smaller blankets placed in specific locations on the patient, head wraps, etc.). As well as preferences may be requested by military experts.

4. Will design recommendations/changes be made to manufacturer when tests show that COTS blankets are not sufficient?
   - Yes, recommendations may be made to develop and custom blankets specific to our needs.

5. What is price of recommended COTS blankets?
   - The prices for the various blankets manufactured by Cincinnati Sub-Zero are given in table 1.

Table 1: List prices for various blankets manufacture by Cincinnati Sub-Zero

	Type	Model	Size	Quantity	Cost
Convective hyper-hypothermia water blankets/wraps	**Single-Use Blanket**	Maxi-Therm	Adult	Box 5	$127.00
			Pediatric	Box 5	$90.00
			Infant	Box 5	$72.00
	Reusable Blanket	Plasti-Pad	Adult	Each	$193.00
			Pediatric	Each	$157.00
			Infant	Each	$129.00
	Reusable Mattress/Pad	Gelli-Roll	Adult	Each	$1,420.00
			Pediatric	Each	$1,180.00
			Infant	Each	$861.00
	Single-Use Wrap for brain cooling	Head Wrap	One Size	Box 10	$2,080.00
Accessories	**Connection Hose**	Compatible All Models	N/A	Each	$63.00

Temperature Sensor Questions

1. What temperature sensors/probes and placement to be used? (Correlation to core temperature)
   - Most commercially available hyper-hypothermia devices currently on the market are able to accommodate multiple temperature sensor probes. The three main temperature probes used are rectal, esophageal, and urethral Foley catheter.
   - The accuracy of a temperature probe can vary depending on the condition and injuries of the patient. Having multiple options of temperature probes is essential for measuring an accurate core body temperature.

2. Interval of temperature measurement?
   - The Blanketrol III from Cincinnati Sub-Zero is able to measure and update the temperature reading on the user display every 5 seconds. The newest version of this system can also come with data logger software which can capture data at the following user chosen rates (30 seconds, 1 minute, 5 minutes, 15 minutes, 30 minutes or 60 minutes).   This capability would be built into the system being designed by Rocky Research.

3. Will the sensor be sold as part of the device?
   - The temperature sensor will likely be sold with the device, but should also be sold separately as an accessory. The temperature sensor may also be sold in disposable or reusable models.

4. What is price of recommended sensors?
   - Cincinnati Sub-Zero sells disposable and reusable temperature probes. The temperature probes are sold in units of 20 and range in price from $93.00 to $158.00. A reusable cable which interfaces with the temperature probe and hyper-hypothermia system is also sold. The cables range in price from $45.00 to $48.00. A port would be built into the system being designed by Rocky Research to interface with the temperature probe.

5. The Working Group made it clear that any device to be considered needs to be non-invasive. Would the temperature probes you suggested make this a more invasive device or are these probes already used to monitor the patient without the warming/cooling device?

- The three main temperature probes (invasive) currently used on the market for hyper-hypothermia devices are rectal, esophageal and the foley catheter. Other non-invasive probes (skin temperature probe) may also be used to interface with the device, though they may not be as accurate in measuring core body temperature. Skin temperature probes are traditionally not as accurate as rectal, esophageal, or foley catheters (generally inaccurate to a degree greater than $1^{o}C$), and are prone to loss of adhesion. In a trauma scenario where heating is desired (prevention of the lethal triad), an accurate core temperature reading is crucial for the function of the body temperature conditioning device. However, in situations where more advanced care is not available the skin temperature probe may be useful for basic preliminary data collection or activation of the system. Once more advanced care becomes available, invasive temperature monitoring should be the preferred method for measuring body temperature. It may be recommended that both types of temperature probes (invasive/non-invasive) be carried as basic accessories for this device.

Prototype Questions

1. Where is User Interface and what information needs to be displayed?
   - The user interface will be similar to existing normothermia systems (figure 3), and will offer simple programmable body temperature regulation. The system will have both an automatic and manual control setting to enable the operator or physician to have control over the patients care. The user interface will display the common patient care information typically found in current commercially available patient warming devices. This includes the following; patient core temperature, water temperature, and the system status which indicates the temperature set point and any necessary corrections to be made by the operator.
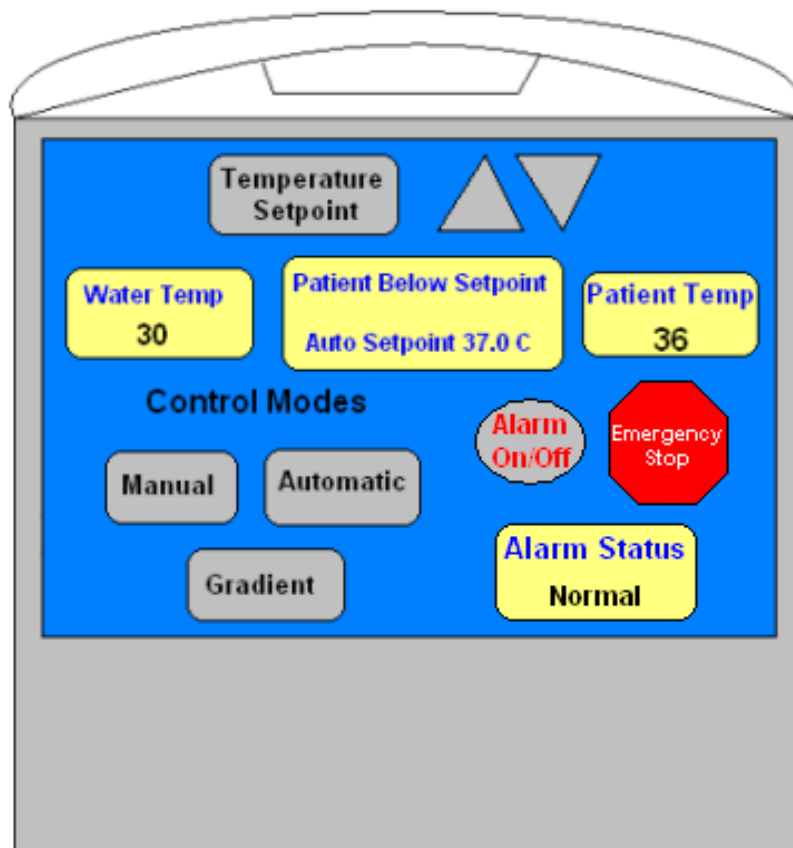

Figure 3. Example of generalized schematic of graphical user interface

2. What are safety parameters for maximum and minimum temperature?
    - Based on existing patient warming systems currently on the market, the allowable patient core temperature control range is approximately 30 – 40°C. Also, the typical water temperature control range is approximately 4 – 42°C. This temperature range allows for sufficient heating and cooling capacity while staying within human thermal comfort ranges and preventing the possibility of thermal burns from the device (Figure 4). Figure 4 describes the relationship between temperature of direct skin contact and exposure time to cause thermal injury. At higher temperatures, a shorter exposure time is required to cause thermal injury. Whereas at lower temperatures, a longer exposure time is required to cause thermal injury. These average temperature ranges are based on the specifications of three commercially available systems; Arctic Sun 5000, Medi-Therm III (MTA-7900), and the Blanketrol III.
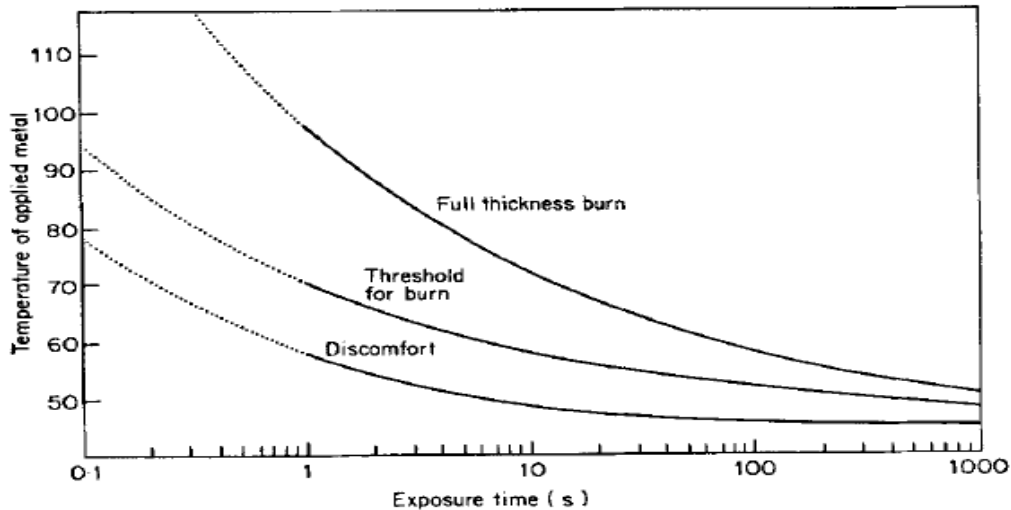

Figure 4. Relationship between temperature of direct skin contact and exposure time to cause thermal injury [1].

3. Include alarm system to avoid dangerous situations (i.e. when X number of failed attempts to adjust temperature).
    - To prevent the system from overheating or cooling the patient, the device will have upper and lower limits of temperature, control systems, automatic shut-off when the temperature exceeds set points, and an alarm system to notify the operator of dangerous temperature situations. As mentioned during the teleconference, a unique feature relevant to military applications may be an on/off switch to the system alarm. This feature would be necessary with use during military applications as the alarm lights or sounds may give away the position of military personnel within a combat zone.

<u>Algorithm to Control Patient Temperature Questions</u>

1. What are your algorithms for temperature management, and what are they based on?
    - The proposed system will have automatic, manual, and a gradient temperature control options. Existing control algorithms for vapor compression systems and water temperature will be modified for patient body temperature. The gradient temperature control (GTC) algorithm is based on multipoint control of surface temperature. The GTC algorithm directly controls the average temperature of all points as well as the temperature difference between each pair of points. The algorithm also includes methods to eliminate the interference of each control output on the other control points. When temperature inputs are received, an average temperature and the temperature differences between each pair of points is calculated. Proportional integral derivative (PID) control is performed for the current value of the control points. PID control is a generic feedback control loop mechanism designed to minimize error. The PID output values are distributed to prevent them from affecting PID control performance at other points, eliminating the possibility of interference.

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2. To initiate use, do you plan to allow the user to prompt rapid cooling or heating verses temperature maintenance? (Thus reducing lag time to let the system figure out what is needed).

- There will be gradient temperature control in addition to auto and manual options

3. For rapid cooling or heating, what is the desired rate a first responder would hope to achieve with standard techniques, and what can the system do within its designed safety range for energy (heat) flux?

- In terms of rapid heating or cooling, the thermal expansion valve (TXV) designed by Rocky Research allows for variable speed system operation of the vapor compression system over a wide range of capacities without damage to the compressor. This allows for the system to reach its maximum cooling or heating value within a short period of time. However, the overall design of the device is mainly to control patient temperature and not specifically the water temperature. Also, the system is designed primarily for temperature management and may not be suitable for rapid heating or cooling of the patient as the conditions and patients injuries may not be feasible.

4. What are safety parameters for maximum and minimum temperature and how do you plan to incorporate this in the algorithm?

- As mentioned above, the safety parameters for temperature will be based on existing patient warming systems currently on the market; the allowable patient core temperature control range is approximately $30 – 40^{o}$C. Also, the typical water temperature control range is approximately $4 – 42^{o}$C. Safety parameters will be included within both the logic control and in the hardware where if one fails the redundant system ensures that there is no over/under shoot of patient temperature.

5. What are your safety parameters for maximum heat flux across the system in contact with the patient, and how do you plan to incorporate this in the algorithm?
- The relationship between heat flux and exposure time to cause thermal injury is described in figure 5. Safety parameters for maximum heat flux between the system and patient will be based on this data. At higher heat flux densities, a shorter exposure time is required to cause thermal injury. Whereas at lower heat flux densities, a longer exposure time is required to cause thermal injury. However, this data is based on skin contact with a heat metal plate and will need to be further evaluated during the patient simulation testing.
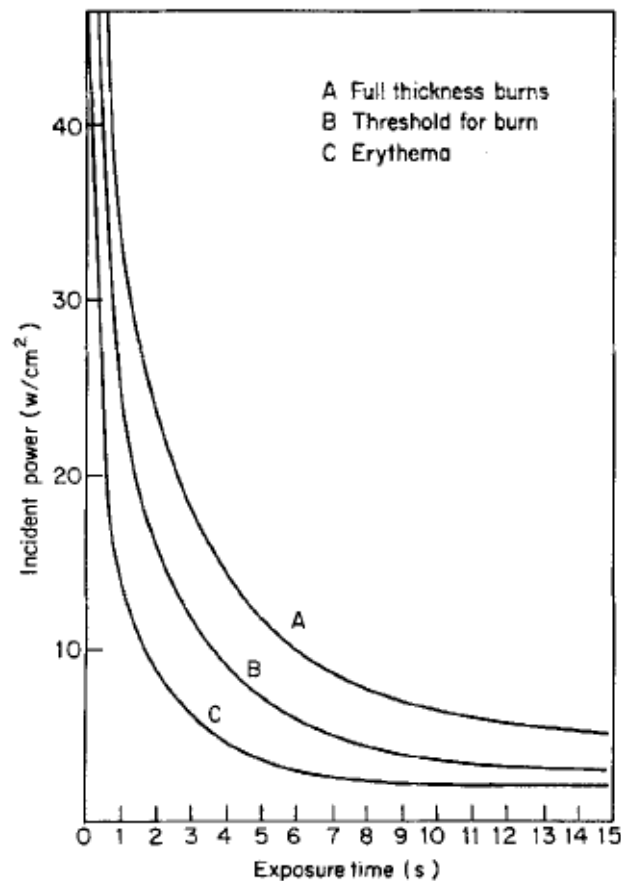
Figure 5. Relationship between heat flux and exposure time to cause thermal injury [1]

6. Will you monitor and display trends (i.e. patient has been steadily losing temperature as x degrees / minute)?

   • Yes, to be determined.

7. If the system notices it cannot compensate for patients temperature changes, how will the system notify the user?
   • The user interface will include a gradient variable button/function which activates the gradient variable mode. The gradient variable mode operation is based on the temperature of the patient relative to the set point temperature. The difference between the set-point and patient core body temperature will be reported. This accounts for situations in which the system is unable to compensate for the patient's temperature changes.

References:
[1] Bull, J.P., Lawrence, J.C., Thermal conditions to produce skin burns. Fire and Materials. 3: 100-105, 1979.